

Fixed point theorems for the pair of coincidentally commuting mappings in d-metric space

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(Received: July 18, 2010; Accepted: September 21, 2010)

ABSTRACT

In this paper common fixed point of pair of coincidentally commuting mappings in D-metric spaces have been proved.

Key words: Common fixed point, D-metric spaces, coincidentally commuting mappings.

INTRODUCTION

Dhage^{1,2,3} introduced the concept of D-metric space and proved several results. Rhoades⁴ also established interesting results on D-metric spaces. Jungck^{5,6} introduced a more general concept known as compatible mapping in metric spaces. Ume⁷ proved non convex minimization theorem in D-metric spaces.

Definition 1

If $\rho(X)$ is a collection of all non-empty bounded subsets of a D-metric space (X, D) and for $A, B, C \in \rho(X)$, let $H(A, B, C) = \sup \{D(a, b, c) : a \in A, b \in B, c \in C\}$, then (1) $H(A, B, C) \geq 0$ and $H(A, B, C) = 0$ implies $A=B=C$, with a singleton, further if $A=B=C$, then $H(A, B, C) =$ perimeter of the largest triangle contained in the set $A > 0$, otherwise A is singleton,

- (1) $H(A, B, C) = H(B, C, A) = H(C, A, B)$,
- (2) $H(A, B, C) \leq H(A, B, E) + H(A, E, C) + H(E, B, C)$

Definition 2

A point $x_0 \in X$ is said to be fixed point if $Tx_0 = x_0$ i.e. a point which remain in variant under a transformation T is called a fixed point.

Coincidentally Commuting Mappings

The commutativity of pairs of maps is vital for proving the common fixed point theorems and Jungck⁵ first used it in the ordinary metric space.

Definition 3

Two maps $f, g : X \rightarrow X$ are said to be commutative or commuting if $fg(x) = gf(x)$ for all $x \in X$.

In an ordinary metric space (X, d) , Sessa⁹ first introduce a weaker version of the commutativity for a pair of self maps of X as follows :

Definition 4

Two maps $f, g : (X, d) \rightarrow (X, d)$ are called weakly commutative or weakly commuting if $d(fg(x), gf(x)) \leq d(fx, gx)$ for all $x \in X$.

It is shown in research paper of Sessa⁹ that a weakly commuting pair of maps in metric space is commuting, but the converse may not be true. In the following we list a few weaker versions of the commutativity for pairs of maps in metric spaces appeared in the earlier literatures.

Definition 5

Jungck⁶, Two maps $f, g : (X, d) \rightarrow (X, d)$ are said to be compatible if

$$\lim_{n \rightarrow \infty} d(fg x_n, gf x_n) = 0,$$

whenever $\{x_n\}$ is a sequence in X satisfying $\lim(fx_n, gx_n) = 0$. It has been shown in Jungck⁹ that every weakly commuting pair of maps is compatible, but the reverse implication may not hold.

Definition 6

Two maps $f, g : X \rightarrow X$ are said to be coincidentally commuting or coincidence preserving if they commute at coincidence points.

Thus we have a one-way implication, namely, commuting maps \Rightarrow weakly commuting maps \Rightarrow compatible maps \Rightarrow coincidentally commuting maps.

Example 1

Let $X = R$ and define $f, g : R \rightarrow R$ by $f(x) = x/2$ and $g(x) = x^2$ for $x \in R$. Clearly there are two coincidence points for the maps f and g in R namely 0 and $1/2$. Note that f and g commute at 0, i.e. $fg(0) = gf(0)$, but $fg(1/2) = 1/8 \neq gf(1/2)$ and so f and g are not coincidentally commuting on R .

Definition 7

Let $S, T : X \rightarrow X$, then the orbit of S and T at a point $x \in X$ is a set $(3) O(S, T; x) = \{x, Sx, TSx, STSx, \dots\}$

Then the D-metric space X is said to be (S, T) -orbitally bounded if the orbit $O(S, T; x)$ is bounded for each $x \in X$. The orbit $O(S, T; x)$ is called complete if every D-Cauchy sequence in $O(S, T; x)$ converges to a point in X . A (S, T) -orbitally complete D-metric space X is one in which every orbit $O(S, T; x)$, $x \in X$, is complete.

Useful lemma in the sequel

Lemma 1. (D-Cauchy Principle)

Let $\{x_n\} \subseteq X$ be bounded with D-bound k satisfying $(4) D(x_n, x_{n+1}, x_m) \leq \alpha^n k$ for all $m > n \in N$ and $0 \leq \alpha \leq 1$, then $\{x_n\}$ is D-Cauchy.

Lemma 2 (D-Cauchy Principle)

Let $\{x_n\} \subseteq X$ be bounded with D-bound k satisfying

$$(5) \quad D(x_n, x_{n+1}, x_m) \leq \phi^n k$$

for all $m > n \in N$, where $\phi: R^+ \rightarrow R^+$ satisfies

$$\sum_{n=1}^{\infty} \phi^n(t) < \infty$$

for each $t \in R^+$. Then $\{x_n\}$ is D-Cauchy.

Lemma 3

If x is (X, T) -orbitally bounded D-metric space and $\{x_n\} \subseteq O(S, T; x)$, $x \in X$ satisfying

$$(6) \quad D(x_n, x_{n+1}, x_m) \leq \phi^n(t), \text{ for all } m > n \in N,$$

$$\text{where } \phi: R^+ \rightarrow R^+ \text{ satisfies } \sum_{n=1}^{\infty} \phi^n(t) < \infty$$

for each $t \in R^+$. Then $\{x_n\}$ is D-Cauchy.

Let Φ denotes the class of all functions $\phi: R^+ \rightarrow R^+$ satisfying

$$(7) \quad \phi \text{ is continuous,}$$

$$(8) \quad \phi \text{ is nondecreasing,}$$

$$(9) \quad \phi(t) < t \text{ for } t > 0,$$

$$(10) \quad \sum_{n=1}^{\infty} \phi^n(t) < \infty \text{ for each } t \in R^+$$

A member ϕ of class Φ is called a control or contraction function and commonly used control function is $\phi(t) = \alpha t$, $0 \leq \alpha < 1$. We need the following lemma in the sequel.

Lemma 4

If $\phi \in \Phi$, then $\lim_{n \rightarrow \infty} \phi^n(t) = 0$ for each $t > 0$ and $\phi^n(0) = 0$ for each $n \in N$.

Below we prove the main result of this paper.

Theorem 1. Let $S, T : X \rightarrow X$ and let X be (S, T) -orbitally complete and (S, T) -orbitally bounded D-metric space and suppose that

$$D(Sx, Ty, z) \leq \phi \alpha \frac{D(x, Sx, z)^2 + D(y, Ty, z)^2}{D(x, Sx, z) + D(y, Ty, z)} + \beta D(x, y, z)$$

for all $x, y \in X$ and $z \in O(S, T; x) \cup O(T, S; y)$, where $0 \leq 2\alpha + \beta < 1$ and $\phi \in \Phi$. Then S and T have a unique common fixed point.

Proof

Let $x \in X$ be arbitrary and define a sequence $\{x_n\} \subset X$ by

$$(12) \quad x_0 = x, x_{2n+1} = Sx_{2n}, x_{2n+2} = Tx_{2n+1}, n \geq 0.$$

We show that $\{x_n\}$ is D-Cauchy. Now for any $m \geq 2$, by (11) we have

$$D(x_1, x_2, x_m) = D(Sx_0, Tx_1, x_m) \\ \leq \phi \alpha \frac{D(x_0, x_1, x_m)^2 + D(x_1, x_2, x_m)^2}{D(x_0, x_1, x_m) + D(x_1, x_2, x_m)} + \beta D(x_0, x_1, x_m)$$

$$\leq \phi(\alpha(D(x_0, x_1, x_m) + D(x_1, x_2, x_m)) + \beta D(x_0, x_1, x_m)) \\ \leq \alpha(D(x_0, x_1, x_m) + \alpha D(x_1, x_2, x_m) + \beta D(x_0, x_1, x_m))$$

$$(13) \quad D(x_1, x_2, x_m) \leq \frac{\alpha + \beta}{1 - \alpha} D(x_0, x_1, x_m)$$

where k is a D-bound of $O(S, T; x)$.

Similarly for $m \geq 3$, we get

$$D(x_2, x_3, x_m) = D(Sx_2, Tx_1, x_m) \\ \leq \phi \alpha + \frac{D(x_2, x_3, x_m)^2 + D(x_1, x_2, x_m)^2}{D(x_2, x_3, x_m) + D(x_1, x_2, x_m)} \beta D(x_1, x_2, x_m) \\ \leq \phi[\alpha(D(x_2, x_3, x_m) + D(x_1, x_2, x_m)) + \beta D(x_1, x_2, x_m)] \\ \leq [\alpha D(x_2, x_3, x_m) + \alpha D(x_1, x_2, x_m) + \beta D(x_1, x_2, x_m)] \\ D(x_2, x_3, x_m) \leq (\alpha + \beta/1-\alpha)D(x_1, x_2, x_m) \leq (\alpha + \beta/1-\alpha)^2 D(x_0, x_1, x_m).$$

In general for $m \geq n + 1$, one has

$$(14) \quad D(x_n, x_{n+1}, x_m) \leq (\alpha + \beta/1-\alpha)^n D(x_0, x_1, x_m)$$

which implies that $\{x_n\}$ is D-Cauchy. Since X is (S, T) orbitally complete,

$\lim_{n \rightarrow \infty} x_n = u$ exists. We show that u is a common fixed point of S and T .

$$\text{Now } D(u, Tu, u) = \lim_{n \rightarrow \infty} D(x_{2n}, Tu, u)$$

$$= \lim_{n \rightarrow \infty} D(Sx_{2n+1}, Tu, u)$$

$$\leq \lim_{n \rightarrow \infty} \phi \alpha \frac{D(x_{2n}, Sx_{2n+1}, u)^2 + D(u, Tu, u)^2}{D(x_{2n}, Sx_{2n+1}, u) + D(u, Tu, u)} + \beta D(x_{2n}, u, u)$$

$$\leq \phi(0 + \alpha D(u, Tu, u) + 0) \leq \phi(\alpha D(u, Tu, u)) \\ < \alpha D(u, Tu, u)$$

$$(15) \quad (1-\alpha) D(u, Tu, u) < 0,$$

which is possible only when $u = Tu$.

Again we get,

$$D(u, Su, u) = D(Su, u, u) = D(Su, Tu, u)$$

$$\leq \phi \alpha \frac{D(u, Su, u)^2 + D(u, u, u)^2}{D(u, Su, u) + D(u, u, u)} + \beta D(u, u, u)$$

$$\leq \phi[\alpha D(u, Su, u)] \leq \alpha D(u, Su, u)$$

$$(16) \text{ and so } u = Su \text{ since } \phi \in \Phi.$$

Thus u is a common fixed point of S and T . To prove uniqueness, let $v(=1)u$ be another common fixed point of S and T . Then $D(u, u, v) \neq 0$ and we get $D(u, v, v) = D(Su, Tv, v)$

$$\leq \phi \alpha \frac{D(u, Su, v)^2 + D(v, Tv, v)^2}{D(u, Su, v) + D(v, Tv, v)^2} + \beta D(u, v, v)$$

$$\leq \alpha D(u, u, v)$$

Again interchanging the role of u and v we obtain $D(v, u, u) \leq \phi(D(v, v, u))$.

$$\text{It follows that } D(u, v, v) \leq \phi^2(D(u, v, v)).$$

Which is a contradiction and hence $u = v$. This completes the proof.

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